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%\begin{document}

\title{Growth estimates, control and structures in a two-field model of the
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%authors with [#1] as link for affiliation

\author{João P. S. Bizarro}
\author{R. Vilela Mendes}

\affil{Instituto de Plasmas e Fusão Nuclear,
Instituto Superior Técnico, Universidade de Lisboa, 1049-001 Lisboa,
Portugal}

% must be present
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%email of corresponding author
\emailID{bizarro@ipfn.tecnico.ulisboa.pt}

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\begin{document}

\maketitle

\begin{abstract}
{
Some properties of a reduced two-dimensional two-fluid (density plus vorticity)
model of the scrape-off layer (SOL) are studied analytically. The model
is built around a conservative system describing transport perpendicular to the
magnetic field in a slab geometry, to which
terms are added to account for diffusion and parallel losses and to mimic plasma
flow from the core.
Nonlinear estimates for growth rates are derived, showing the growth in the
density gradient to be controlled by
the vorticity gradient, and vice-versa, thus suggesting
a nonlinear instability in the model. Control of fluctuations by means of a
biasing potential is assessed, being shown negative polarisations are
more effective in decreasing plasma turbulence in the SOL,
hence explaining what is seen in experiments. Exact
solutions for the conservative part of the equations are obtained in the form of
travelling waves, which might be the conservative ancestors of the collective
structures (so-called blobs) observed both in experiments and in numerical
simulations.}
\end{abstract}

\section{Introduction}
Transport in the plasma scrape-off layer (SOL) is one of the main issues
pertaining to the operation of future fusion machines, the
physics of particle and energy flows in this boundary controlling both the
machine performance and the life expectancy of plasma-facing materials
[1,2]. %\cite{Stangeby,Naulin,Roth,Boedo}.

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Modelling of the SOL being extremely complex
 %\cite{Zeiler,Garcia,Scott,Ricci1,Ricci2,Kendl}
 [3], numerical codes have been developed
 with recourse to reduced two-field models and conservation laws, which greatly
 simplifies the analysis of SOL transport while retaining the fundamental
 properties of the underlying physics
 %\cite{Garbet,Philippe1,Philippe2,Figurella,Colin}
 [4-6]. The broad picture emerging is that, although small-scale turbulence
 dominates,
 there may be large-scale coherent structures (associated with
 intermittent events known as blobs) that are observed both in experiments and in
 computations, and greatly contribute to the nature of transport in the SOL
 %\cite{Naulin,Boedo,Garcia,Ricci2,Kendl,Philippe1,Philippe2,Figurella,Krasheninn
 ikov,Furno,Bodi,Theiler,Maggs}%
 [2,3,5-7]. Such blobs generate machine-scale flows that lead to thermal
 charge asymmetries, impurity deposition and, through nonlinear interaction
 with small-scale turbulence, change in the local transport properties.

Here one will approach these
 questions through the study of a reduced two-dimensional (2D) fluid model
 for plasma dynamics (electrons plus current) perpendicular to the
 magnetic field, built from a conservative model [8] %\cite{Izacard}
 (itself a cold-ion, reduced version of more complete four-field models
 [9]) %\cite{Morrison,Hazeltine}
 to which phenomenological terms are added accounting
 for particle and current diffusion, parallel losses and a core-plasma source
 [4-6].

%\cite{Philippe1,Philippe2,Figurella,Colin}
 Emphasis will be on
 obtaining nonlinear growth estimates for the physical quantities
 and on discussing the eventual control of fluctuations by polarization [5,10].
 %\cite{Philippe2,Figurella,Colin,Silva1,Silva2}
 Focusing on the conservative
 part of the equations, one will also aim at deriving exact solutions that
 might be the conservative ancestors of the collective structures related
 with blobs.

\section{The model}

\label{SecII}

The starting point is the two-field (density plus vorticity) model

$$\begin{aligned} &\partial_t \ln \left(\frac{\phi}{B} \right) - \left(\frac{\phi}{B} \right) \nabla^2 \phi \\ &+ \nabla^2 \left(\frac{\phi}{B} \right) \nabla^2 \phi \end{aligned} \quad \text{\label{Eq.1}}$$

describing dynamics perpendicular to the magnetic field, which can be
 extracted from a four-field model including finite-Larmor-radius effects,
 drift-velocity ordering and gyroviscous terms [9] %\cite{Morrison}

, provided the

dynamics along the magnetic field (the so-called parallel dynamics) is
 suppressed, the poloidal magnetic fluctuations are neglected and the
 cold-ion limit is taken [8]. %\cite{Izacard}

Hereabove, $\ln \left(x_1, x_2, t \right)$ stands

for the logarithm of the normalised density $n \left(x_1, x_2, t \right)$,
 $\phi \left(x_1, x_2, t \right)$ for the normalised electrostatic potential,
 and $B \left(x_1 \right)$

for the normalised magnetic field, $x_1 = \left(r - a \right)$ and $x_2 = a \theta$
 $x_2 = a \theta$ are the radial and poloidal coordinates, respectively, with a
 a the minor radius of the core plasma (space being rescaled by the ion
 sonic Larmor radius and time by the ion cyclotron frequency), the canonical
 Poisson

bracket $\left[f, h \right]$ is given by

$$\left[f, h \right] = \partial_1 f \partial_2 h - \partial_2 f \partial_1 h,$$

and the del operator reads $\nabla = \left(\partial_1, \partial_2 \right)$, with $\partial_i = \partial / \partial x_i$.

To this conservative model one adds, as is usually found in the literature [5,6],

diffusive terms, governed by the diffusion coefficients D for particles and ν for vorticity, as well as the parallel losses to the walls or limiters, determined (from sheath physics [1,4]) by the plasma

floating potential Λ and some $\sigma_{||}$ measuring the characteristic time for parallel transport, and also a source term $S(x_1)$, accounting for the plasma

flow from the core. Hence, and putting $\tilde{g} = g - \partial_1 \left(1/B \right)$, ([Eq.1](#)) becomes

$$\begin{aligned} & \partial_1 \Lambda / \partial t = - \left[\phi, \Lambda \right] - \tilde{g} \partial_1 \Lambda \\ & \partial_2 \left(\Lambda - \phi \right) + D \left(\nabla^2 \Lambda + \left[\nabla \Lambda, \nabla \phi \right] \right) - \sigma_{||} e^{-\left(\Lambda - \phi \right)} + S \\ & \partial_1 \nabla^2 \phi / \partial t = - \left[\phi, \nabla^2 \phi \right] - g \partial_2 \Lambda + \nu \nabla^4 \phi + \sigma_{||} \left[1 - e^{-\left(\Lambda - \phi \right)} \right] \end{aligned}$$

\label{Eq.5}

which accounts for particle balance (for electrons) and charge conservation, respectively. The model in ([Eq.5](#)) is very much the same as a 2D model used for flux-driven uniform-temperature (so-called FDUT) simulations [6], and also very similar to the

extensively studied model TOKAM-2D [4,5],

the difference with the latter lying in the presence hereabove of the term associated with the magnetic field

inhomogeneity \tilde{g} in the continuity equation, so all results in this paper apply to TOKAM-2D by making $\tilde{g} = 0$. The compressibility term in ([Eq.5](#)), namely, $\tilde{g} \partial_1 \Lambda$, being of the same order as the coupling term $g \partial_2 \Lambda$ in the vorticity equation, one has decided to keep it in the model.

Nonlinear growth estimates

SecIII

To estimate the dependence of the growth rate of physical quantities, ([Eq.5](#)) will be simplified by assuming the difference $\phi \left(x_1, x_2, t \right)$

is negligible, and that the parallel current losses are compensated by the source $S \left(x_1 \right)$ (a quasi-equilibrium hypothesis). Therefore, one expects

the following equations to display the same qualitative behavior as those in ([Eq.5](#)):

$$\begin{aligned} & \partial_1 \Lambda / \partial t = - \left[\phi, \Lambda \right] - \tilde{g} \partial_1 \Lambda \\ & \partial_2 \left(\Lambda - \phi \right) + D \left(\nabla^2 \Lambda + \left[\nabla \Lambda, \nabla \phi \right] \right) - \sigma_{||} \end{aligned}$$

$$\frac{\partial}{\partial t} \nabla^2 \phi - \frac{\partial}{\partial t} \nabla^2 \phi = - \left[\phi, \nabla^2 \phi \right]$$

Then, defining

$\nabla^2 \phi = \left(\frac{\partial}{\partial x}, - \frac{\partial}{\partial y} \right) f$,
 which is such that $\left[f, h \right] = \nabla f \cdot \nabla^2 h$,
 (\ref{Eq.8}) becomes

$$\frac{\partial}{\partial t} \nabla^2 \phi - \nabla^2 \phi = - \nabla \phi \cdot \nabla^2 \phi - \tilde{g} \frac{\partial}{\partial t} \nabla^2 \phi + D \left(\nabla^2 \phi \right) \left(\nabla^2 \phi \right) \quad \text{\nonumber}$$

$$\frac{\partial}{\partial t} \nabla^2 \phi - \nabla^2 \phi = - \nabla \phi \cdot \nabla^2 \phi - \nabla^2 \phi \frac{\partial}{\partial t} \nabla^2 \phi - \tilde{g} \frac{\partial}{\partial t} \nabla^2 \phi + D \left(\nabla^2 \phi \right) \left(\nabla^2 \phi \right) \quad \text{\label{Eq.10}}$$

One now assumes the solution of (\ref{Eq.10}) to be defined in a domain D with either periodic boundary conditions or vanishing values for all functions at its boundary, meaning, in practice, that boundary terms can be dropped in all partial integrations.

This simplifying assumption may not seem fully appropriate to the boundary between the SOL and the core plasma (at $x_1=0$), yet any eventual non-vanishing boundary terms would not be dynamical, but fixed instead, and hence one does not expect them to qualitatively change the inequalities obtained below.

The growth rates thus estimated are global as well as nonlinear, in the sense that they proceed from the model equations without any previous linearisation of the latter

(unlike in the approach followed below when addressing the control of fluctuations).

So, multiplying the second of equations (\ref{Eq.10}) by ϕ on the left and integrating over D yields

$$\frac{1}{2} \frac{d}{dt} \int_D \left| \nabla \phi \right|^2 = \int_D g \phi \frac{\partial}{\partial t} \nabla^2 \phi - \nu \int_D \left(\nabla^2 \phi \right) \left(\nabla^2 \phi \right) \quad \text{\label{Eq.11}}$$

whence the inequality

$$\frac{d}{dt} \int_D \left| \nabla \phi \right|^2 \leq \int_D \left| \nabla \phi \right|^2 + \int_D \left(g \phi \right)^2, \quad \text{\label{Eq.12}}$$

which means the growth of $|\nabla \phi|^2$ is partially controlled by the gradient $|\nabla \ln|$ of the logarithm of the electron density.

Proceeding to the first of equations (\ref{Eq.10}) to establish a bound on the growth of $|\nabla \ln|$, one takes the gradient of this equation, makes the inner product with $\nabla \ln$ and integrates by parts on the domain D to obtain

$$\frac{1}{2} \frac{d}{dt} \int_D \left| \nabla \ln \right|^2 = \int_D \left(\nabla \phi \cdot \nabla^2 \ln - D \left| \nabla \ln \right|^2 \right) \left(\nabla^2 \ln \right) + \int_D \tilde{g} \frac{\partial}{\partial t} \nabla^2 \ln \left(\nabla^2 \ln \right) - \int_D D \left(\nabla^2 \ln \right)^2, \quad \text{\label{Eq.14}}$$

so the following inequality follows

$$\frac{d}{dt} \int_D \left| \nabla \ln \right|^2 \leq 3 \int_D \left| \nabla \phi \right|^2 + \int_D \left(2 + D \left| \nabla \ln \right|^2 \right) \left(\nabla^2 \ln \right)^2 + D \left| \nabla \ln \right|^2 \left(\nabla^2 \ln \right)^2 \quad \text{\label{Eq.15}}$$

\end{equation}

The growth of $\left\| \nabla n \right\|$ is thus bounded by $\left\| \nabla \phi \right\|$, whose growth is itself bounded by $\left\| \nabla n \right\|$, suggesting a nonlinear instability (at least for some domains of the configuration space).

\section{Control of fluctuations} \label{SecIV}

A route for plasma control in the SOL (highly desirable for tokamak operation) is via polarisation, either of the wall (biased limiter or divertor elements) or using biased probes, an approach that has been tested both numerically [5] and experimentally [10].

\cite{Silva1,Silva2}

and by means of numerical simulations [5].

\cite{Philippe2,Figurella,Colin}.

Here, the model in (\ref{Eq.5}) will be used to understand how

control of fluctuations might be achieved with the aid of biasing.

So, let $n(x_1)$ and $V_{\text{bias}}(x_1, t)$ be such that

\begin{align}

$$n^{(0)}(x_1) \left(x_1 \right) = n_0 - \mu^{-1} x_1 \quad \text{\nonumber}$$

$$\phi^{(0)}(x_1, t) = \Lambda + V_{\text{bias}}(x_1, t) \quad \text{\nonumber}$$

\label{Eq.17}

\end{align}

is a solution of (\ref{Eq.5}) with Λ replaced by $\Lambda + V_{\text{bias}}(x_1, t)$, μ giving the scale length for the exponential decay of density in the SOL.

One expects $V_{\text{bias}}(x_1, t)$ to be of the form

\begin{equation}

$$V_{\text{bias}}(x_1, t) = U(x_1, t) e^{-\left(Z - x_1 \right) / \lambda_D} \quad \text{\label{Eq.19}}$$

\end{equation}

Z being the radial width of the SOL, λ_D the

Debye length, and $U(x_1, t)$ a slowly varying function of x_1 and t . The intensity $U(x_1, t)$ of the potential taken at

the wall or at a probe would be a control parameter, whilst the decaying term in $V_{\text{bias}}(x_1, t)$

takes into account the screening properties of the plasma away from $x_1 = Z$.

If one now looks for fluctuations around the unperturbed solution (\ref{Eq.17}), one may write up to first order,

\begin{align}

$$n(x_1, x_2, t) = n^{(0)}(x_1) + \delta n(x_1, x_2, t) \quad \text{\nonumber}$$

$$\phi(x_1, x_2, t) = \phi^{(0)}(x_1, t) + \delta \phi(x_1, x_2, t) \quad \text{\nonumber}$$

$$\phi(x_1, x_2, t) = \phi^{(0)}(x_1, t) + \delta \phi(x_1, x_2, t) \quad \text{\label{Eq.21}}$$

$$\phi(x_1, x_2, t) = \phi^{(0)}(x_1, t) + \delta \phi(x_1, x_2, t) \quad \text{\label{Eq.21}}$$

\end{align}

and subsequently plug (\ref{Eq.17}) and (\ref{Eq.21}) into (\ref{Eq.5}) to obtain,

\begin{align}

$$\partial_t \delta n - \partial_x \left(\mu^{-1} \partial_x \delta n \right) - \partial_x \left(\partial_x \phi \right) = -\partial_x \left(\partial_x \phi \right) \quad \text{\nonumber}$$

+ \sigma

$$\left| \nabla^2 \delta n - \mu^{-1} \partial_x \delta n \right| \quad \text{\nonumber}$$

$$\nabla^2 \delta \phi - \partial_t \delta \phi = -\partial_x \left(\partial_x \phi \right) \quad \text{\nonumber}$$

$$\nabla^2 \delta \phi - \partial_t \delta \phi = -\partial_x \left(\partial_x \phi \right) + \partial_x \left(\partial_x \phi \right) \quad \text{\nonumber}$$

$$\nabla^2 \delta \phi - \partial_t \delta \phi = -\partial_x \left(\partial_x \phi \right) + \partial_x \left(\partial_x \phi \right) \quad \text{\nonumber}$$

} \delta \phi
 + \nu \nabla ^{4} \delta \phi. \label{Eq.23}
 \end{align}

Fourier transforming (\ref{Eq.23}), keeping only the lowest-order terms in convolution products, setting $\nu \simeq \sigma_{\perp} \simeq 0$, and putting $k = \sqrt{k_1^2 + k_2^2}$ yields for the damping/growth rates

$$\begin{aligned} & \gamma_{\perp} \simeq \left(\left| k_2 \right| / 2 k \right) \sqrt{4g \left(\mu^{-1} - \tilde{g} \right) - \left(\tilde{g} k^2 - \partial_{1}^3 \phi^{(0)} / k \right)^2}, \end{aligned} \label{Eq.35}$$

whenever the quantity under the square root is non-negative. The solutions of (\ref{Eq.23}) will not grow indefinitely (and become unstable) provided

$$4g \left(\mu^{-1} - \tilde{g} \right) k^2 \leq \left(\tilde{g} k^2 - \partial_{1}^3 \phi^{(0)} / k \right)^2, \label{Eq.36}$$

which recovers the driving effect of a negative density gradient (a positive μ) and the stabilising role of the third derivative of the potential that have been known for $\tilde{g} = 0$ \cite{Philippe2}.

A physical interpretation of (\ref{Eq.36}) is possible if, from (\ref{Eq.17}) and (\ref{Eq.19}), one notices

$\phi^{(0)} = \Lambda + U_0 e^{-Z/\Lambda_D}$ is the potential at a distance Z from the polarisation probe. Introducing the distance to the probe as a parameter, assuming a negative density gradient in the SOL, and neglecting the derivatives of the slowly varying $U(x_1, t)$ in (\ref{Eq.19}), (\ref{Eq.36}) reads %can be expressed in terms of physical variables as

$$\begin{aligned} & 4 k^2 \left[\left| \partial_{1} \right| \left(1/B \right) \right] \leq \left[\left| \partial_{1} \right| / n - \left(1/B \right) \right] \left[k^2 \left(1/B \right) - U_0 e^{-Z/\Lambda_D} / \Lambda_D^3 \right]^2. \end{aligned} \label{Eq.37}$$

It follows from (\ref{Eq.37}) that control of unstable modes is a local effect and becomes increasingly difficult further away from the probe (because of the e^{-Z/Λ_D} term), and also that

a negative polarisation U_0 is more favourable than a positive one (accounting for the fact that, in general, $\left| \partial_{1} \right| \left(1/B \right) \geq 0$ in a tokamak), whereas for positive U_0 the less controllable modes occur around $k^2 \simeq U_0 e^{-Z/\Lambda_D} / \Lambda_D^3$.

In agreement with the advantage predicted here of using a negative U_0 , experiments have indeed shown that negative biasing leads not only to a larger improvement in particle confinement, but it also reduces the propagation of large-scale events (or blobs) and lowers the amplitude of fluctuations [10]. \cite{Silva1,Silva2}.

That it is preferable to apply a negative (as opposed to a positive) bias could not be predicted from the TOKAM-2D model because

$\tilde{g} = 0$ there [5], \cite{Garbet,Philippe1,Philippe2,Figurella,Colin} and with $\tilde{g} = 0$ (\ref{Eq.37}) would read $4 k^2 \left[\left| \partial_{1} \right| \left(1/B \right) \right] \leq \left(U_0 e^{-Z/\Lambda_D} / \Lambda_D^3 \right)^2$ instead, a condition where the sign of U_0 has no influence

whatsoever.

\section{Structures and conservative dynamics} \label{SecV}

Many dynamical systems of physical interest have both conservative and dissipative components, having been proven finite-dimensional vector fields always correspond to a superposition of Hamiltonian and gradient components \cite{Vilela1}. Identifying the Hamiltonian component is important because it often happens that in some regions of phase space the effect of the non-conservative components cancels out along a neighbourhood of some of the Hamiltonian orbits, implying the full system ends up displaying deformed versions of the latter, which led to the notion of "constants of motion in dissipative systems" \cite{Vilela1}.

It is conceivable that a similar situation might apply in infinite dimensions as one of the tools used for the finite-dimensional vector field decomposition, namely the Hodge-De Rahm theorem, can be extended to infinite dimensions \cite{Arai}.

For the physical problem dealt with in this paper, the implication is that looking for solutions of the conservative part of the model in (\ref{Eq.10}), which reads

$$\begin{aligned} & \partial_t \nabla \cdot \nabla \phi - \nabla \cdot \nabla \phi \cdot \nabla \tilde{g} \partial_t \nabla \cdot \nabla \phi \\ & \partial_t \nabla \cdot \nabla \phi - \nabla \cdot \nabla \phi \cdot \nabla \tilde{g} \partial_t \nabla \cdot \nabla \phi \end{aligned} \quad \text{\label{Eq.39}}$$

one might at

least obtain the ancestors of coherent structures that might also exist in the full model. So, after transforming according to $\tilde{L}_n(x_1, x_2, t) = \tilde{L}_n(x_1, x_2, t) - \tilde{g}x_1$ and $\tilde{\phi}(x_1, x_2, t) = \tilde{\phi}(x_1, x_2, t) - \tilde{g}x_1$ whilst assuming $\tilde{g} = \tilde{g}$ constant, looking for travelling-wave solutions of the form $\tilde{L}_n(x_1, x_2, t) = \tilde{L}_n(x_1 - v_1 t, x_2 - v_2 t)$ and $\tilde{\phi}(x_1, x_2, t) = \tilde{\phi}(x_1 - v_1 t, x_2 - v_2 t)$, defining $y_i = x_i - v_i t$ and making $\partial_i = \partial / \partial y_i$ henceforth, and putting $\tilde{\phi}(y_1, y_2) = F(y_1, y_2) + v_2 y_1 - v_1 y_2$, (\ref{Eq.39}) reduces to%

$$\begin{aligned} & \partial_1 F \partial_2 \tilde{L}_n - \partial_1 \tilde{L}_n \partial_2 F \\ & \partial_1 F \partial_2 \nabla^2 F - \partial_1 \nabla^2 F \partial_2 F \\ & - g \partial_2 \tilde{L}_n + \tilde{g} \partial_2 \nabla^2 F. \end{aligned} \quad \text{\label{Eq.45}}$$

The first equation in (\ref{Eq.45}) can be seen to be satisfied for $\tilde{L}_n = f(F)$, with f an arbitrary differentiable function, so substitution in the second equation yields

$$\begin{aligned} & \partial_1 F \partial_2 \nabla^2 F - \partial_1 \nabla^2 F \partial_2 F \\ & F \partial_2 F + g \partial_2 f(F) - \tilde{g} \partial_2 \nabla^2 F \\ & = 0, \end{aligned} \quad \text{\label{Eq.47}}$$

which admits a variety of solutions, depending on the choice of $f(F)$. The symmetry exhibited by (\ref{Eq.45}) allows one to identify

still another type of solutions, those of the form $F(y_1, y_2) = F_{\text{rms}}(y_1, y_2)$ and $\tilde{L}_n = \Theta_{\text{rms}} F_{\text{rms}}$, with Θ_{rms} and F_{rms} an operator and a function symmetric in y_1 and y_2 , meaning $F_{\text{rms}}(y_2, y_1) = F_{\text{rms}}(y_1, y_2)$ and

$\Theta_{\text{rms}} F_{\text{rms}}(y_2, y_1) = \Theta_{\text{rms}} F_{\text{rms}}(y_1, y_2)$, in which case (Eq.45) reduces to

$$\partial_{y_2} \Theta_{\text{rms}} F_{\text{rms}} - \tilde{g} \partial_{y_2}^2 F_{\text{rms}} = 0. \quad \text{Eq.46d}$$

Particular solutions can be obtained by making

$F(y_1, y_2) = \alpha F$,

with α constant, and writing

$F(y_1, y_2) = \tilde{F}(y_1, y_2) + \tilde{g} y_1$,

in which case (Eq.47) takes the form

$$\partial_{y_1} \tilde{F} \partial_{y_2}^2 \tilde{F} - \partial_{y_1}^2 \tilde{F} \partial_{y_2} \tilde{F} = -\alpha g \partial_{y_2} \tilde{F}. \quad \text{Eq.50}$$

Two obvious solutions to the homogeneous counterpart of (Eq.50) are $\tilde{F}_0(y_1, y_2) = A e^{\left(k_1 y_1 + k_2 y_2\right)}$ and

$\tilde{F}_0(y_1, y_2) = A \cos\left(k_1 y_1 + k_2 y_2\right) + B \sin\left(k_1 y_1 + k_2 y_2\right)$

so that, plugging into (Eq.50) the ansatz

$\tilde{F}(y_1, y_2) = \tilde{F}_0(y_1, y_2) + \tilde{H}(y_1) \mp \left(\alpha g / k^2\right) y_1$, one gets

$$\partial_{y_1}^3 \tilde{H} \mp k^2 \partial_{y_1} \tilde{H} = 0, \quad \text{Eq.55}$$

whose solutions can be trivially found.

Eventually more localised solutions to (Eq.39) can be derived from (Eq.46d) by noting the Laplacian ∇^2 is symmetric in y_1 and y_2 ,

so putting $\Theta_{\text{rms}} F_{\text{rms}} = (\tilde{g}/g) \nabla^2 F_{\text{rms}}$ and choosing (amongst various possibilities)

$F_{\text{rms}}(y_1, y_2) = A e^{-\gamma(y_1^2 + y_2^2)/2}$ leads to

$$\begin{aligned} L_n(x_1, x_2, t) &= -\frac{\tilde{g}}{g} \gamma A e^{-\gamma \left[(x_1 - v_1 t)^2 + (x_2 - v_2 t)^2 \right] / 2} \\ &+ \left[(x_2 - v_2 t)^2 \right] \tilde{g} x_1 \nonumber \\ \phi(x_1, x_2, t) &= A e^{-\gamma \left[(x_1 - v_1 t)^2 + (x_2 - v_2 t)^2 \right] / 2} + v_2 \left[(x_1 - v_1 t) - v_1 \left[(x_2 - v_2 t) - \tilde{g} x_1 \right] \right]. \quad \text{Eq.65} \end{aligned}$$

The time evolution for a possible $L_n(x_1, x_2, t)$ given by (Eq.65) is shown in Fig.~(Fig.1), which depicts a large-scale structure that is initially located at the inner SOL region and starts moving essentially outwards.

To retain here is the existence of conservative solutions that move concentrations of particles and energy along both radial- and poloidal-like directions in a 2D cross-section, eventually ejecting them from the core to the wall, basically mimicking the behaviour of

blobs observed in experiments and in simulations [2,3,5-7].

%\cite{Naulin,Boedo,Garcia,Ricci2,Kendl,Riva,Philippe2,Bisai1,Bisai2,Krasheninnikov,Furno,Bodi,Theiler}.

\begin{figure}[t]

\centering

\includegraphics[width=0.8\textwidth]{Gaussian_blob_gama50.eps}

\caption{Snapshots with contour plots of the logarithmic density function $\ln n$ for the solution (\ref{Eq.65}) of the conservative system (\ref{Eq.39}), for $A=-1.0$, $v_{1}=0.03$, $v_{2}=0.05$, $\gamma=50.0$ and $g=\tilde{g}=0.1$, the magnitude of contour levels decreasing linearly from red to violet across the rainbow pattern.} \label{Fig.1}

\end{figure}

Of course, these are solutions only to the conservative part of the equations, with

diffusion, parallel losses and source not being accounted for.

However, inspection of (\ref{Eq.5}) suggests that, in the first equation, the role of the

unspecified source term is to compensate for the parallel losses and that, in the second

equation, the longitudinal conductance term will not play a determinant

role as long as fluctuations away from the plasma potential are not

very large. Therefore, it is not unlikely that the overall structure of the complete

solutions will be mostly determined by the conservative dynamics induced by (\ref{Eq.39}).

\section{Summary and conclusions}

\label{SecVI}

A theoretical analysis has been provided on various aspects of a two-fluid model describing SOL turbulence

in slab geometry that retains the magnetic field inhomogeneity terms in the continuity equation.

The model equations have a conservative kernel governing transport across magnetic field lines, plus extra terms

that account for diffusion, longitudinal losses (along the magnetic field) and a plasma core source.

It has been shown that an upper bound for the growth rate of the vorticity gradient depends on (hence is controlled by) the density gradient and that, inversely,

an upper bound for the growth rate of the latter depends on the former, which seems to indicate the presence in the model of a nonlinear instability, with both quantities working together to pull their gradients further and further up.

The possibility of controlling the turbulent fluctuations in model quantities by means of a biasing potential has also been assessed,

having been demonstrated that negative is more favourable than positive bias, thus providing a theoretical explanation for experimental observations pointing in the same direction.

Finally, model equations have been analytically solved for their conservative part and

exact solutions of the travelling-wave type have been derived, some of which propagate from the inner to the outer plasma layers and might, therefore, be interpreted as the conservative ancestors of the collective, large-scale structures identified as blobs in experiments and in computations.

\newpage

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\begin{figure}[tc]
\centering

\includegraphics[width=1.0\textwidth]{Wave_cos2.eps}
\caption{Six snapshots with contour plots of the logarithmic density function
 ρ for the solution (\ref{Eq.57}) of the conservative system (\ref{Eq.39}),
with
 $B=C_0=C_1=C_2=0$, $\alpha=A=1$, $v_1=v_2=0.1$, $k_1=0.2$,
 $k_2=1$ and $g=\tilde{g}$
 $=0.1$, the magnitude of contour levels decreasing linearly from red to violet
across the rainbow pattern.} \label{Fig.1}
\end{figure}

\begin{figure}[tc]
\centering
\includegraphics[width=1.0\textwidth]{Wave_exp2.eps}
\caption{Six snapshots with contour plots of the logarithmic density function
 ρ for the solution (\ref{Eq.62}) of the conservative system (\ref{Eq.39}),
for
 $C_0=C_1=C_2=0$, $\alpha=A=1$, $v_1=-0.2$, $v_2=-0.1$, $k_1=-0.5$,
 $k_2=-1$ and $g=\tilde{g}$
 $=0.1$, the magnitude of contour levels decreasing linearly from red to violet
across the rainbow pattern.} \label{Fig.2}
\end{figure}

Another solution to the homogeneous counterpart of (\ref{Eq.50}) is

$$\tilde{F}_0(y_1, y_2) = A e^{\left(k_1 y_1 + k_2 y_2\right)},$$

\label{Eq.58}

hence, putting

$$\tilde{F}(y_1, y_2) = \tilde{F}_0(y_1, y_2) + \tilde{H}(y_1) - \frac{\alpha g}{k^2} y_1,$$

\label{Eq.59}

(\ref{Eq.50}) becomes

$$\partial_1^3 \tilde{H} - k^2 \partial_1 \tilde{H} = 0,$$

\label{Eq.60}

whose general solution reads [see (n) in the appendix]

$$\tilde{H}(y_1) = C_0 + C_1 e^{k y_1} + C_2 e^{-k y_1}.$$

\label{Eq.61}

On account of this, the functions

$$\begin{aligned} \phi(x_1, x_2, t) &= \alpha \left[\phi(x_1, x_2, t) - v_2 \left(x_1 - v_1 t \right) + v_1 \left(x_2 - v_2 t \right) \right] \\ &+ \left(\alpha - 1 \right) \tilde{g} x_1 \\ \phi(x_1, x_2, t) &= \left(v_2 + \tilde{g} - \frac{\alpha g}{k^2} \right) \left(x_1 - v_1 t \right) \\ &- v_1 \left(x_2 - v_2 t \right) - \tilde{g} x_1 \\ &+ A e^{\left[k_1 \left(x_1 - v_1 t \right) + k_2 \left(x_2 - v_2 t \right) \right]} + C_0 + \\ &C_1 e^{k \left(x_1 - v_1 t \right)} + C_2 e^{-k \left(x_1 - v_1 t \right)} \end{aligned}$$

\label{Eq.62}

are also solutions to (\ref{Eq.39}), snapshots of $\rho(x_1, x_2, t)$
 ρ hereabove being given in figure~\ref{Fig.2}

for $C_0=C_1=C_2=0$, $\alpha=A=1$, $v_1=-0.2$, $v_2=-0.1$,
 $k_1=-0.5$, $k_2=-1$ and $g=\tilde{g}$
 $=0.1$. One sees, also in this case, a large-scale structure that is initially

located at the inner SOL region and subsequently starts moving essentially outwards.

The important point to retain here is the existence of solutions that move concentrations of particles and energy along both (radial- and poloidal-like) directions in a 2D cross-section, eventually ejecting them from the core to the wall, hence mimicking the basic, gross behaviour depicted by blobs that is observed in experiments and

n

\cite{Naulin,Boedo,Garcia,Ricci2,Kendl,Riva,Philippe2,Bisai1,Bisai2,Krasheninnikov,Furno,Bodi,Theiler}.

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\begin{figure}[tc]
\centering
\includegraphics[width=1.0\textwidth]{Gaussian_blob_gama15.eps}
\caption{Six snapshots with contour plots of the logarithmic density function
 $\ln n$  for the solution (\ref{Eq.65}) of the conservative system (\ref{Eq.39}),
for  $A=-1.0$ ,  $v_{1}=0.03$ ,
 $v_{2}=0.05$ ,  $\gamma=15.0$  and  $g=\tilde{g}$ 
 $=0.1$ , the magnitude of contour levels decreasing linearly from red to violet
across the rainbow pattern.} \label{Fig.3}
\end{figure}
```